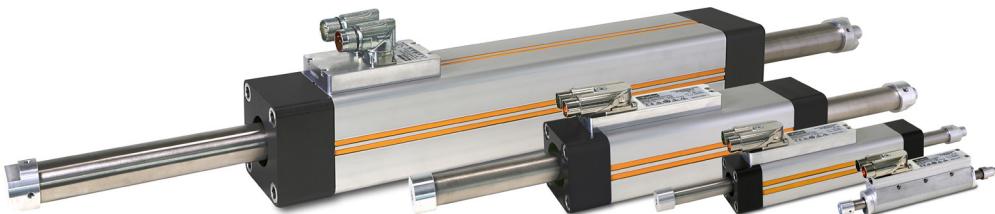


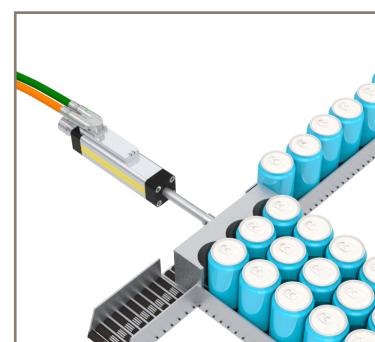


aerospace  
climate control  
**electromechanical**  
filtration  
fluid & gas handling  
hydraulics  
pneumatics  
process control  
sealing & shielding



## ETT - Electric Tubular Motor

Linear Handling and Pick & Place Applications



ENGINEERING YOUR SUCCESS.



#### ***WARNING – USER RESPONSIBILITY***

**FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.**

- This document and other information from Parker-Hannifin Corporation, its subsidiaries and authorized distributors provide product or system options for further investigation by users having technical expertise.
- The user, through its own analysis and testing, is solely responsible for making the final selection of the system and components and assuring that all performance, endurance, maintenance, safety and warning requirements of the application are met. The user must analyze all aspects of the application, follow applicable industry standards, and follow the information concerning the product in the current product catalog and in any other materials provided from Parker or its subsidiaries or authorized distributors.
- To the extent that Parker or its subsidiaries or authorized distributors provide component or system options based upon data or specifications provided by the user, the user is responsible for determining that such data and specifications are suitable and sufficient for all applications and reasonably foreseeable uses of the components or systems.

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# Parker Hannifin

## The global leader in motion and control technologies

### Global Product Design

Parker Hannifin has more than 40 years experience in the design and manufacturing of drives, controls, motors and mechanical products. With dedicated global product development teams, Parker draws on industry-leading technological leadership and experience from engineering teams in Europe, North America and Asia.

### Local Application Expertise

Parker has local engineering resources committed to adapting and applying our current products and technologies to best fit our customers' needs.

### Manufacturing to Meet Our Customers' Needs

Parker is committed to meeting the increasing service demands that our customers require to succeed in the global industrial market. Parker's manufacturing teams seek continuous improvement through the implementation of lean manufacturing methods throughout the process. We measure ourselves on meeting our customers' expectations of quality and delivery, not just our own. In order to meet these expectations, Parker operates and continues to invest in our manufacturing facilities in Europe, North America and Asia.

### Electromechanical Worldwide Manufacturing Locations

#### Europe

Littlehampton, United Kingdom  
Dijon, France  
Offenburg, Germany  
Filderstadt, Germany  
Milan, Italy

#### Asia

Wuxi, China  
Jangan, Korea  
Chennai, India

#### North America

Rohnert Park, California  
Irwin, Pennsylvania  
Charlotte, North Carolina  
New Ulm, Minnesota



Offenburg, Germany

### Local Manufacturing and Support in Europe

Parker provides sales assistance and local technical support through a network of dedicated sales teams and authorized technical distributors throughout Europe.

For contact information, please refer to the Sales Offices on the back cover of this document or visit [www.parker.com](http://www.parker.com)



Milan, Italy



Littlehampton, UK



Filderstadt, Germany



Dijon, France

# Electric Tubular Motor - ETT

## Overview

### Description

ETT is a direct thrust linear motor actuator, ideally suited to all kinds of linear handling and pick & place applications. It is a cost-effective and energy-efficient alternative to pneumatic cylinders in applications that demand greater flexibility and control.

The ETT's linear motion is directly generated without the need for mechanical transmission elements like ball screws, toothed belts and gearboxes. The tubular motor has two main components; the rod (shaft) and the stator with integrated feedback (body). The shaft is made of a stainless steel tube with built in neodymium magnets, which thanks to their high performance, are able to deliver impressive thrust values up to 2083 N. The main body comprises the stator winding, the feedback electronics and high performance bearings. A major benefit of the ETT design is that long and/or heavy duty cycles are possible without the need for additional cooling. The IP67 protection class allows the ETT tubular motor to be used in harsh environmental conditions.

### Features

- Ultra dynamic linear motion and position control capabilities
- Ideally suited for pneumatic substitution where greater position control capabilities are required
- Four lengths and four sizes meeting the requirements of the pneumatic ISO flange standard (DIN ISO 15552:2005-12) for simplified mechanical integration
- Swivelling electrical connectors and extensive accessory options allow flexible mounting
- Reduced mechanical complexity delivers high energy efficiency and reduces maintenance
- AISI304 stainless steel shaft allows it's use in "clean" environments
- High thermal efficiency improves reliability and increases mechanical life
- Wide choice of rod end mounting options, including swivel rod eye, increases flexibility

### Target markets

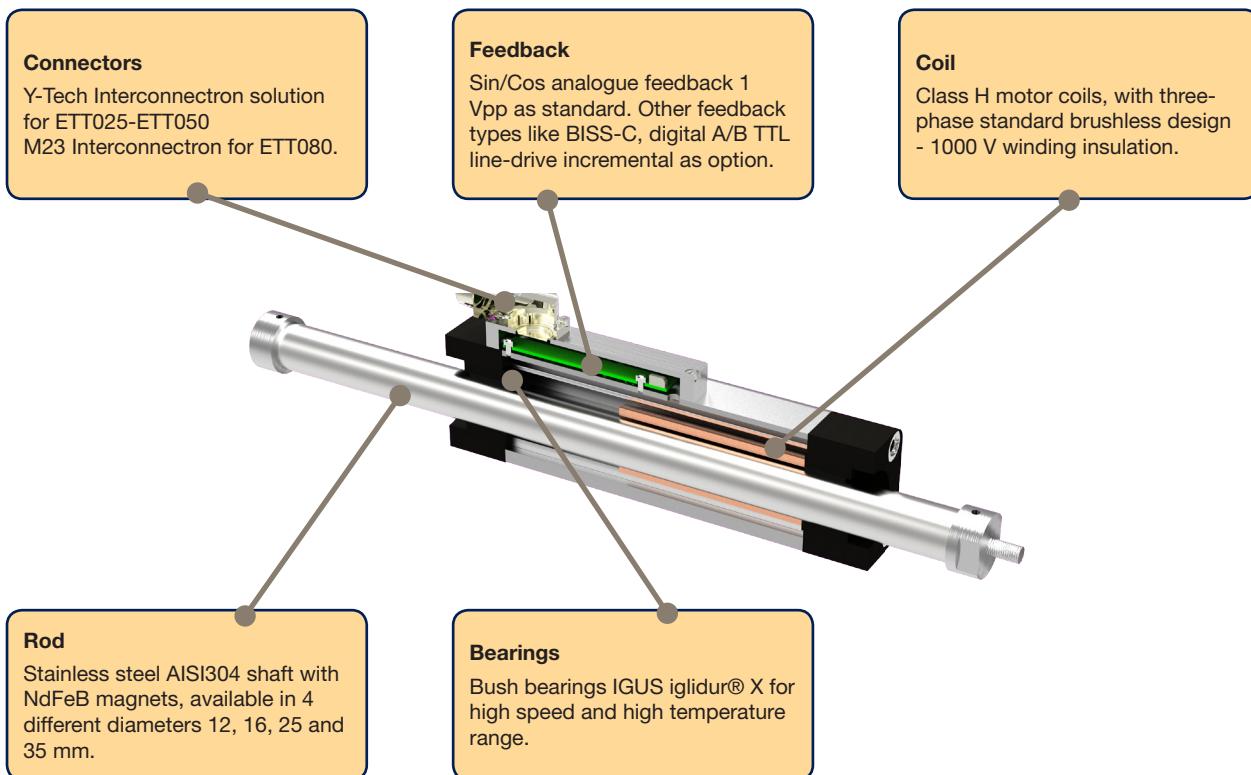
- Food, Pharmaceutical & Beverage
- Packaging Machines
- Material Handling
- Factory Automation



### Technical Characteristics - Overview

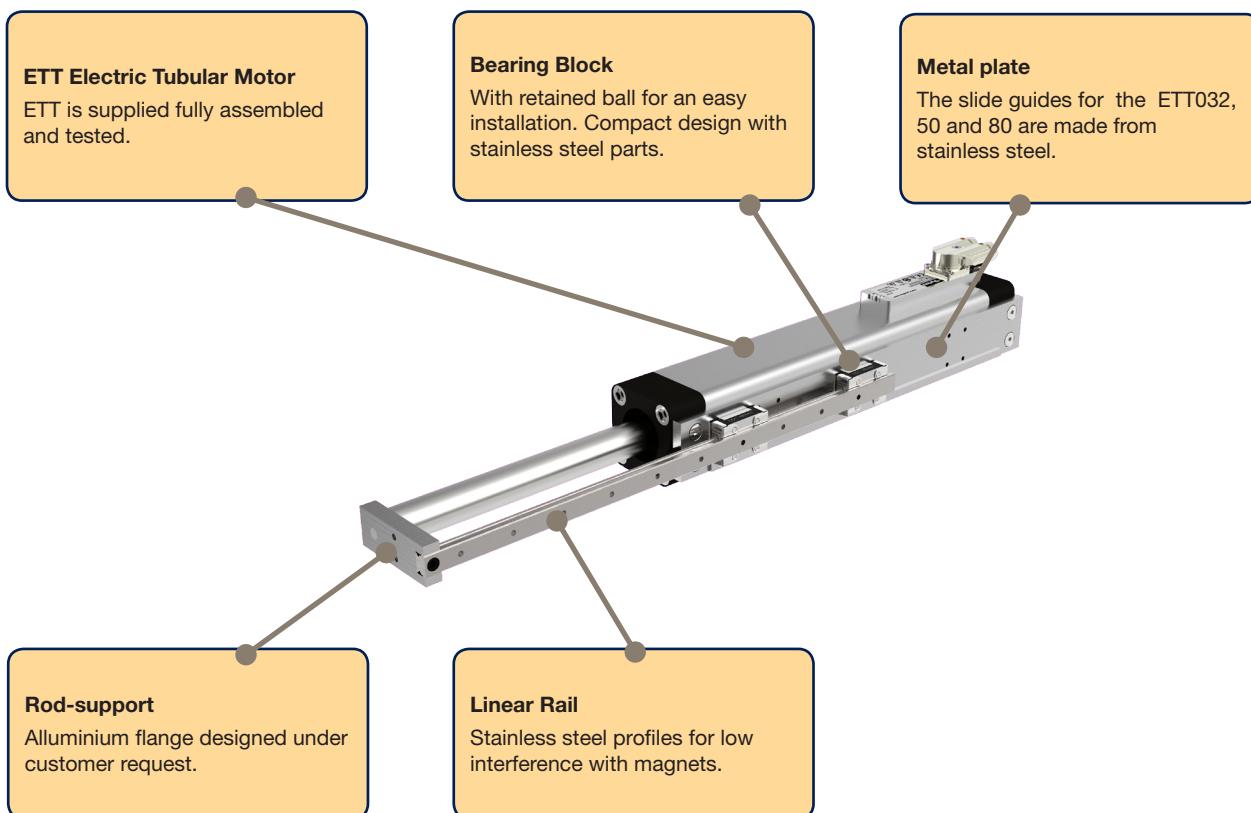
<b>Motor type</b>	Linear tubular servo motor
<b>Rod</b>	AISI304 (stainless steel)
<b>Rated force</b>	8...295 N
<b>Peak force</b>	56...2083 N
<b>Speed range</b>	up to 8 m/s
<b>Acceleration range</b>	up to 350 m/s <sup>2</sup>
<b>Mounting</b>	Screw fixed
<b>Shaft end</b>	Front male thread, Rear cap end Other options available
<b>Cooling</b>	Natural ventilation
<b>Protection level (IEC60034-5)</b>	IP67
<b>Feedback sensor</b>	Analog Hall 1Vpp (SinCos 90°) Other feedback on request
<b>Thermal protection</b>	KTY PTC or PT1000 as option
<b>Marking</b>	CE
<b>Voltage supply</b>	230 VAC (all sizes) 400 VAC (only ETT80)
<b>Temperature class</b>	Class F
<b>Connections</b>	Connectors Flying leads as option
<b>Bi-directional accuracy</b>	0.5 mm

## Product Design ETT Tubular Motor



## Product Design ETT Tubular Motor with Slide Guide System

For more information please check page 20



# Technical Characteristics

## Technical Data

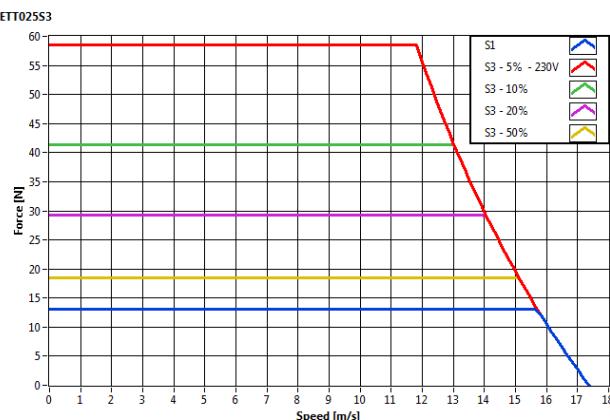
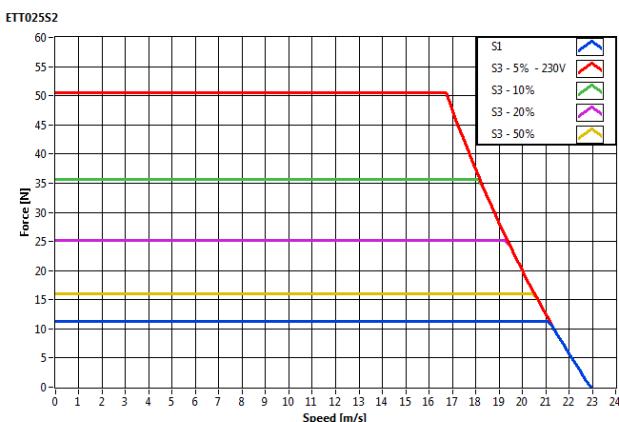
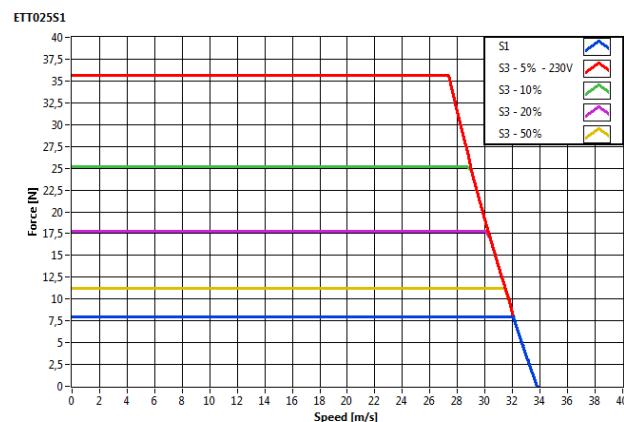
### ETT025

ETT025	Unit	ETT025S1*	ETT025S2	ETT025S3*
Peak force <sup>1) 2) 4)</sup>	[N]	56	80	93
Peak current	[A]	4.8	4.6	4.0
<i>Without heatsink plate</i>				
Continuous stall force duty cycle S1 <sup>1)</sup>	[N]	8	11	13
Continuous stall current duty cycle S1 <sup>1)</sup>	[A]	0.7	0.7	0.6
Force @ duty cycle S3 5% <sup>1)</sup>	[N]	36	50	59
Current @ duty cycle S3 5% <sup>1)</sup>	[A]	3.0	2.9	2.6
Force constant	[N/A]	11.80	17.37	22.95
Back EMF (ph-ph,rms)	[V <sub>rms</sub> /(m/s)]	6.81	10.03	13.25
Phase resistance	[ohm]	17.17	25.06	33.89
Phase inductance	[mH]	5.42	7.89	10.46
Power supply (drive side)	VAC		230	
Max DC bus voltage	VDC		325	
Pole pitch			60	
Maximum stroke <sup>5)</sup>	[mm]		360	
Peak acceleration <sup>3)</sup>	[m/s <sup>2</sup> ]	155	220	254
Position repeatability	[mm]		0.05	
Accuracy	[mm]		0.5	

<sup>1)</sup> Data valid at an ambient temperature of 25 °C; <sup>2)</sup> Based on triangular move over maximum stroke with normal payload

<sup>3)</sup> Based on a 100 mm stroke, without payload; <sup>4)</sup> Considering a duty cycle of S3 2%; <sup>5)</sup> Other value under request

Manufacturing tolerance ±10%; \*Duty cycle S1 and S3 compliant to CEI EN60034-1 with max time 5 minutes



Curves based on rod movement.

Curves based on a theoretical system without load and without stroke limits. Max. duty cycle 5 minutes.

These ratings are valid for Parker Hannifin drives. Other drives might not achieve the same ratings.

Electric Tubular Motor - ETT  
Technical Characteristics

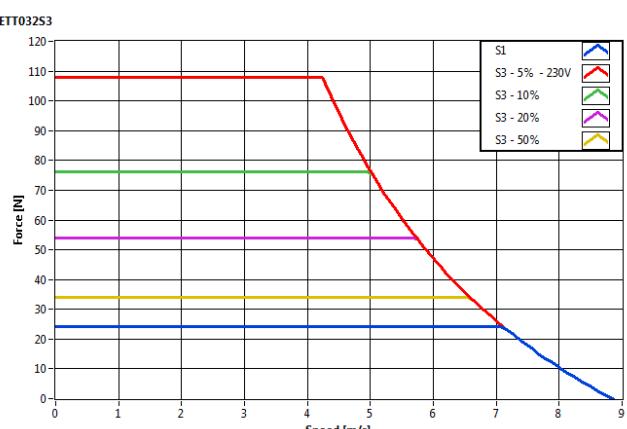
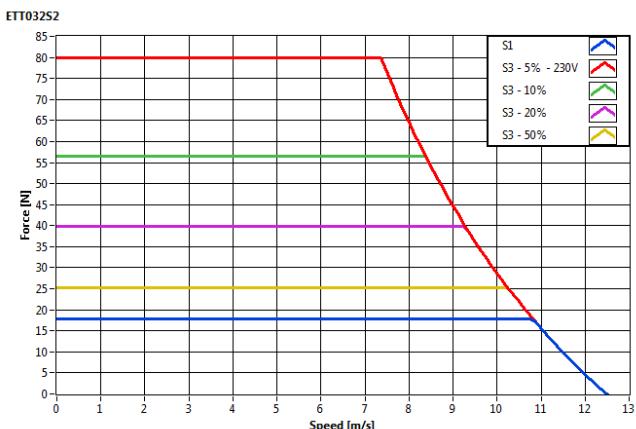
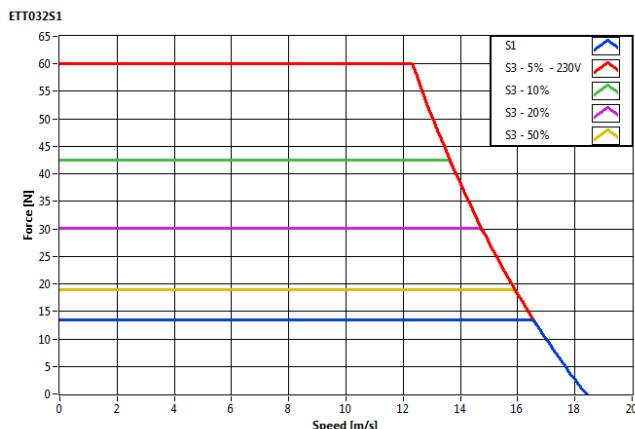
**ETT032**

ETT032	Unit	ETT032S1*	ETT032S2	ETT032S3*
Peak force <sup>1) 2) 4)</sup>	[N]	95	126	169
Peak current	[A]	4.4	4.0	3.8
<i>Without heatsink plate</i>				
Continous stall force duty cycle S1 <sup>1)</sup>	[N]	13	18	24
Continous stall current duty cycle S1 <sup>1)</sup>	[A]	0.6	0.6	0.5
Force @ duty cycle S3 5% <sup>1)</sup>	[N]	60	80	107
Current @ duty cycle S3 5% <sup>1)</sup>	[A]	2.8	2.5	2.4
Force constant	[N/A]	21.67	31.89	45.05
Back EMF (ph-ph,rms)	[V <sub>rms</sub> /(m/s)]	12.51	18.41	26.01
Phase resistance	[ohm]	31.46	43.84	58.50
Phase inductance	[mH]	14.57	21.75	28.94
Power supply (drive side)	VAC		230	
Max DC bus voltage	VDC		325	
Pole pitch			60	
Maximum stroke <sup>5)</sup>	[mm]	660	630	600
Peak acceleration <sup>3)</sup>	[m/s <sup>2</sup> ]	224	258	307
Position repeatability	[mm]		0.05	
Accuracy	[mm]		0.5	

<sup>1)</sup> Data valid at an ambient temperature of 25 °C; <sup>2)</sup> Based on triangular move over maximum stroke with normal payload

<sup>3)</sup> Based on a 100 mm stroke, without payload; <sup>4)</sup> Considering a duty cycle of S3 2%; <sup>5)</sup> Other value under request

Manufacturing tolerance ±10%; \*Duty cycle S1 and S3 compliant to CEI EN60034-1 with max time 5 minutes.



Curves based on rod movement.

Curves based on a theoretical system without load and without stroke limits. Max. duty cycle 5 min.

These ratings are valid for Parker Hannifin drives. Other drives might not achieve the same ratings.

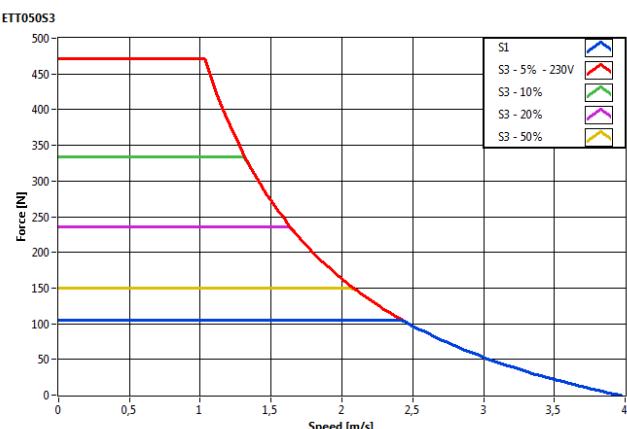
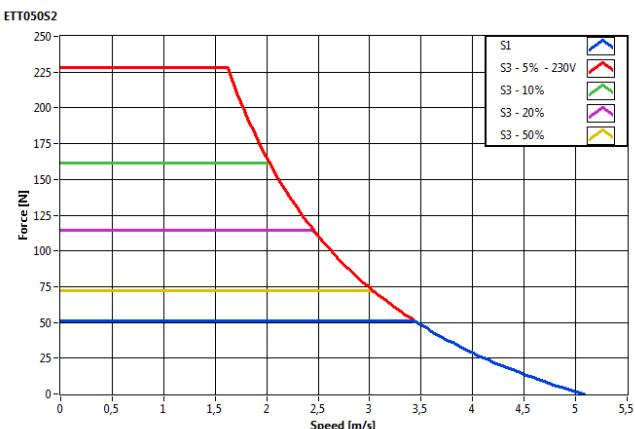
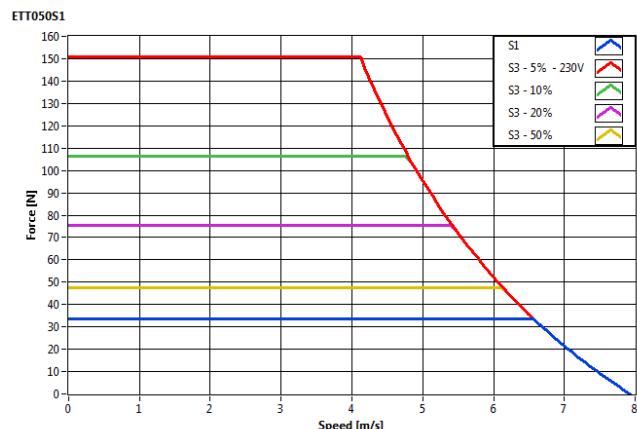
## ETT050

ETT050	Unit	ETT050S1*	ETT050S2	ETT050S3*
Peak force <sup>1) 2) 4)</sup>	[N]	238	361	746
Peak current	[A]	4.7	4.6	7.4
<i>Without heatsink plate</i>				
Continous stall force duty cycle S1 <sup>1)</sup>	[N]	34	51	106
Continous stall current duty cycle S1 <sup>1)</sup>	[A]	0.7	0.7	1.1
Force @ duty cycle S3 5% <sup>1)</sup>	[N]	151	228	472
Current @ duty cycle S3 5% <sup>1)</sup>	[A]	3.0	2.9	4.7
Force constant	[N/A]	50.30	78.55	100.53
Back EMF (ph-ph,rms)	[V <sub>rms</sub> /(m/s)]	41.07	64.13	82.08
Phase resistance	[ohm]	42.41	62.70	58.04
Phase inductance	[mH]	23.55	34.70	22.70
Power supply (drive side)	VAC		230	
Max DC bus voltage	VDC		325	
Pole pitch			60	
Maximum stroke <sup>5)</sup>	[mm]	720	690	540
Peak acceleration <sup>3)</sup>	[m/s <sup>2</sup> ]	199	264	337
Position repeatability	[mm]		0.05	
Accuracy	[mm]		0.5	

<sup>1)</sup> Data valid at an ambient temperature of 25 °C; <sup>2)</sup> Based on triangular move over maximum stroke with normal payload

<sup>3)</sup> Based on a 100 mm stroke, without payload; <sup>4)</sup> Considering a duty cycle of S3 2%; <sup>5)</sup> Other value under request

Manufacturing tolerance ±10%; \*Duty cycle S1 and S3 compliant to CEI EN60034-1 with max time 5 minutes.



Curves based on rod movement.

Curves based on a theoretical system without load and without stroke limits. Max. duty cycle 5 min.

These ratings are valid for Parker Hannifin drives. Other drives might not achieve the same ratings.

Electric Tubular Motor - ETT  
Technical Characteristics

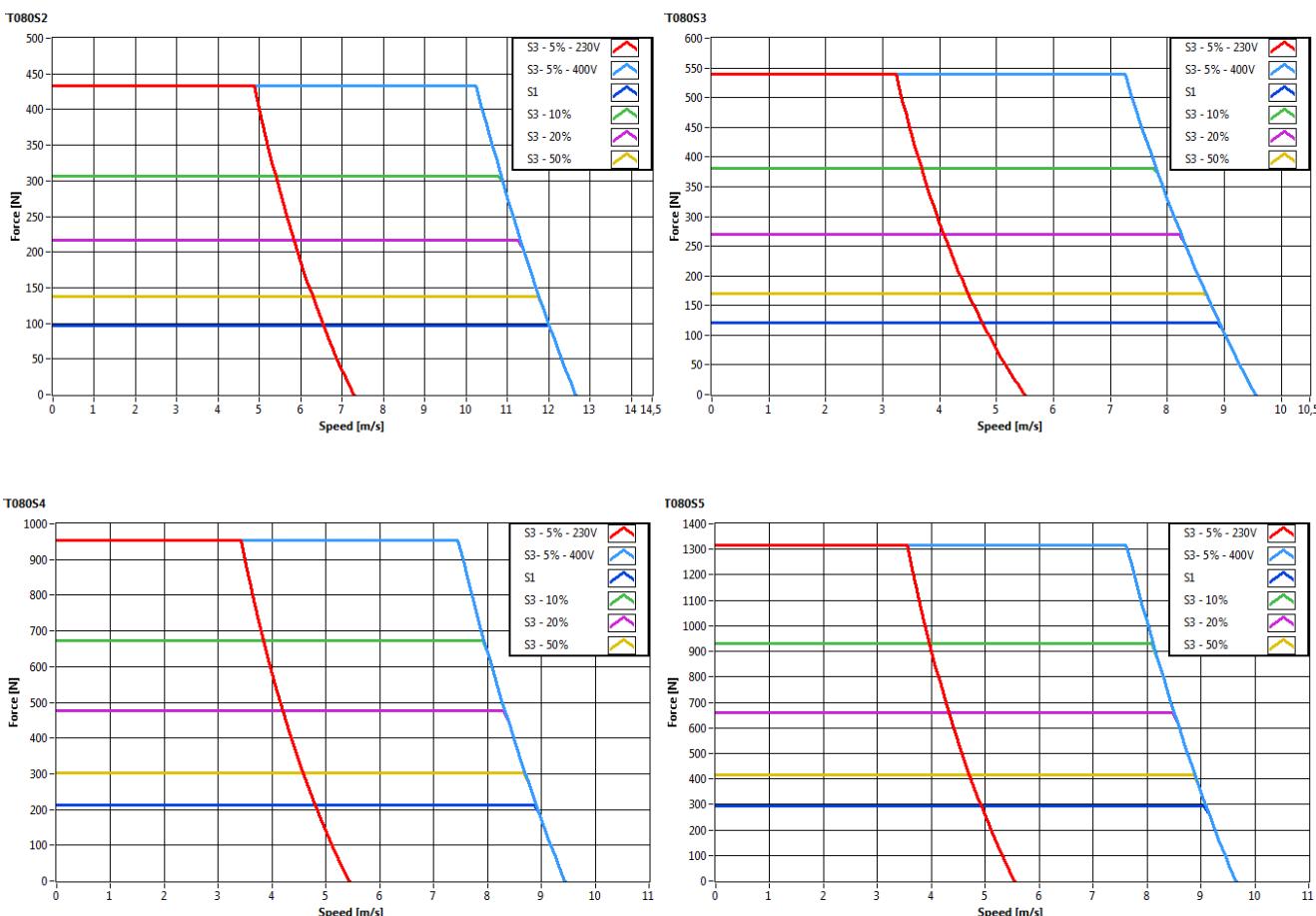
**ETT080**

<b>ETT080 Power supply 230-400 VAC</b>	<b>Unit</b>	<b>ETT080S2</b>	<b>ETT080S3*</b>	<b>ETT080S4</b>	<b>ETT080S5</b>
<b>Peak force</b> <sup>1) 2) 4)</sup>	[N]	686	852	1506	2083
<b>Peak current</b>	[A]	12.5	11.7	20.5	29.0
<i>Without heatsink plate</i>					
<b>Continous stall force duty cycle S1</b> <sup>1)</sup>	[N]	97	120	213	295
<b>Continous stall current duty cycle S1</b> <sup>1)</sup>	[A]	1.8	1.7	2.9	4.1
<b>Force @ duty cycle S3 5% <sup>1)</sup></b>	[N]	434	539	952	1318
<b>Current @ duty cycle S3 5% <sup>1)</sup></b>	[A]	7.9	7.4	13.0	18.3
<b>Force constant</b>	[N/A]	54.80	72.57	73.44	71.88
<b>Back EMF (ph-ph,rms)</b>	[V <sub>rms</sub> /(m/s)]	31.64	59.26	42.4	41.5
<b>Phase resistance</b>	[ohm]	11.14	14.81	7.65	5.25
<b>Phase inductance</b>	[mH]	12.80	17.06	7.50	5.51
<b>Power supply (drive side)</b>	VAC	230/400			
<b>Max DC bus voltage</b>	VDC	325/566			
<b>Pole pitch</b>		60			
<b>Maximum stroke</b> <sup>5)</sup>	[mm]	736	706	586	460
<b>Peak acceleration</b> <sup>3)</sup>	[m/s <sup>2</sup> ]	238	264	330	352
<b>Position repeatability</b>	[mm]	0.05			
<b>Accuracy</b>	[mm]	0.5			

<sup>1)</sup> Data valid at an ambient temperature of 25 °C; <sup>2)</sup> Based on triangular move over maximum stroke with normal payload

<sup>3)</sup> Based on a 100 mm stroke, without payload; <sup>4)</sup> Considering a duty cycle of S3 2%; <sup>5)</sup> Other value under request

Manufacturing tolerance ±10%; \*Duty cycle S3 compliant to CEI EN60034-1 with max time 5 minutes.



Curves based on road movement.

Curves based on a theoretical system without load and without stroke limits. Max. duty cycle 5 min.

These ratings are valid for Parker Hannifin drives. Other drives might not achieve the same ratings.

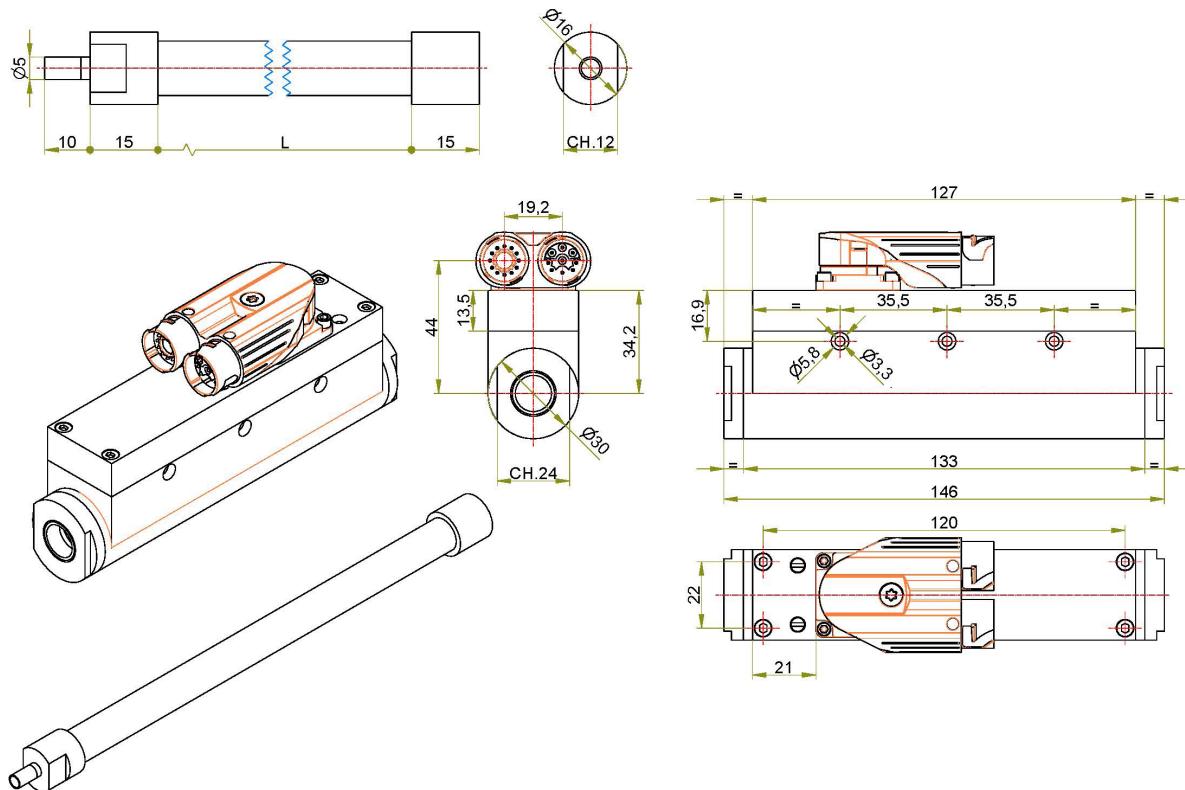
## Standards and Conformance

<b>Low Voltage Directive</b>	• 2006/95/EC
<b>EMC Directive</b>	• 2004/108/EC
<b>Generic standard - Emission standard for industrial environments</b>	• CEI EN 61000-6-4:2007
<b>Generic standard - Immunity for industrial environments</b>	• CEI EN 61000-6-2:2006

Marked 

## Dimensions

### ETT025



### ETT - Length of Rod / Table of Stroke

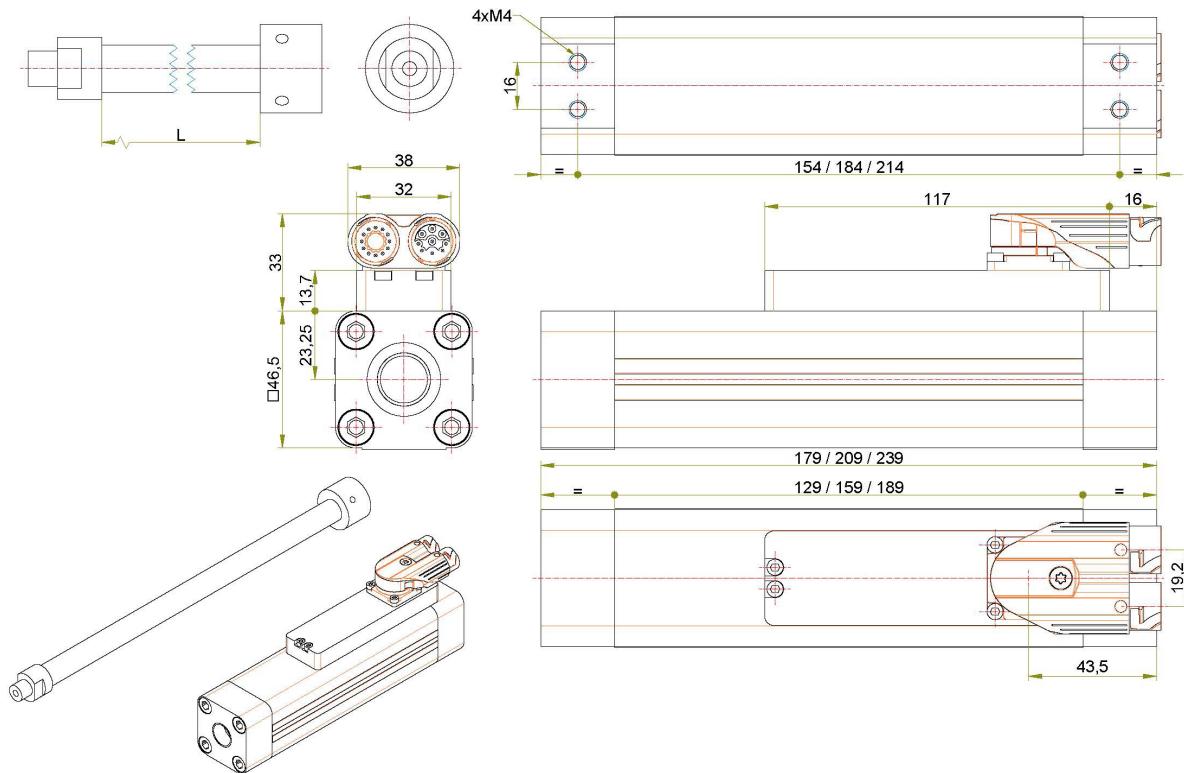
### ETT025

Part Number Codification	Rod "F"		Rod "N"		Rod "M"		Rod "G"		Stroke		
	Length [mm]	Weight [kg]	S1 [mm]	S2 [mm]	S3 [mm]						
0205	204	0.216	216	0.216	206	0.216	212	0.217	20	20	20
0215	214	0.23	226	0.23	216	0.23	222	0.231	30	30	30
0245	244	0.271	256	0.271	246	0.271	252	0.272	60	60	60
0275	274	0.311	286	0.311	276	0.311	282	0.312	90	90	90
0305	304	0.352	316	0.352	306	0.352	312	0.353	120	120	120
0335	334	0.393	346	0.393	336	0.393	342	0.394	150	150	150
0365	364	0.434	376	0.434	366	0.434	372	0.435	180	180	180
0395	394	0.475	406	0.475	396	0.475	402	0.476	210	210	210
0425	424	0.515	436	0.515	426	0.515	432	0.516	240	240	240
0455	454	0.556	466	0.556	456	0.556	462	0.557	270	270	270
0485	484	0.597	496	0.597	486	0.597	492	0.598	300	300	300
0515	514	0.638	526	0.638	516	0.638	522	0.639	330	330	330
0545	544	0.679	556	0.679	546	0.679	552	0.68	360	360	360
Coil weight [kg]										0.5	0.5
										0.6	

Max rod length allowed 750 mm.

## Dimensions

### ETT032



### ETT - Length of Rod / Table of Stroke

### ETT032

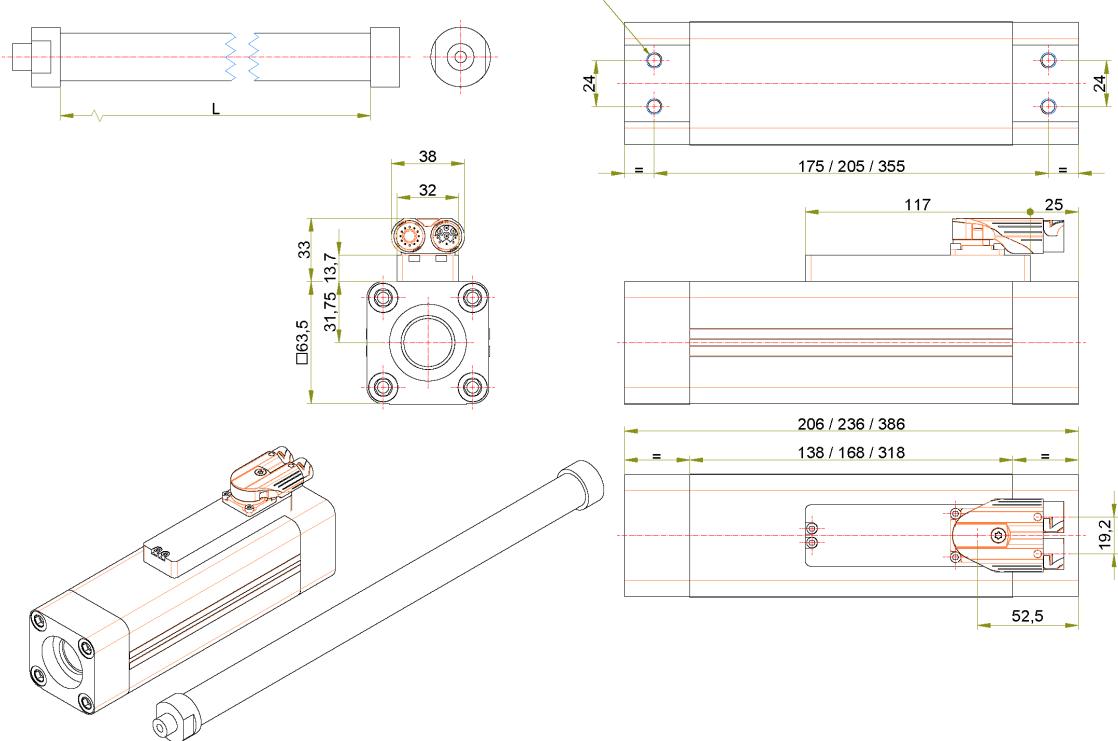
Part Number Codification	Rod "F"		Rod "N"		Rod "M"		Rod "G"		Stroke		
	Length [mm]	Weight [kg]	Length [mm]	Weight [kg]	Length [mm]	Weight [kg]	Length [mm]	Weight [kg]	S1 [mm]	S2 [mm]	S3 [mm]
0221	227	0.185	239	0.184	228	0.184	237	0.186	30		
0251	257	0.227	269	0.226	258	0.226	267	0.228	60	30	
0281	287	0.268	299	0.267	288	0.267	297	0.269	90	60	30
0311	317	0.31	329	0.309	318	0.309	327	0.311	120	90	60
0341	347	0.352	359	0.351	348	0.351	357	0.353	150	120	90
0371	377	0.394	389	0.393	378	0.393	387	0.395	180	150	120
0401	407	0.436	419	0.435	408	0.435	417	0.437	210	180	150
0431	437	0.478	449	0.477	438	0.477	447	0.479	240	210	180
0461	467	0.519	479	0.518	468	0.518	477	0.52	270	240	210
0491	497	0.561	509	0.56	498	0.56	507	0.562	300	270	240
0521	527	0.603	539	0.602	528	0.602	537	0.604	330	300	270
0551	557	0.645	569	0.644	558	0.644	567	0.646	360	330	300
0581	587	0.687	599	0.686	588	0.686	597	0.688	390	360	330
0611	617	0.729	629	0.728	618	0.728	627	0.73	420	390	360
0641	647	0.771	659	0.77	648	0.77	657	0.772	450	420	390
0671	677	0.812	689	0.811	678	0.811	687	0.813	480	450	420
0701	707	0.854	719	0.853	708	0.853	717	0.855	510	480	450
0731	737	0.896	749	0.895	738	0.895	747	0.897	540	510	480
0761	767	0.938	779	0.937	768	0.937	777	0.939	570	540	510
0791	797	0.98	809	0.979	798	0.979	807	0.981	600	570	540
0821	827	1.022	839	1.021	828	1.021	837	1.023	630	600	570
0851	857	1.063	869	1.062	858	1.062	867	1.064	660	630	600
Coil weight [kg]									0.89	1.01	1.16

Max rod length allowed 1250 mm.

Electric Tubular Motor - ETT  
Dimensions

**Dimensions**

**ETT050**



**ETT - Length of Rod / Table of Stroke**

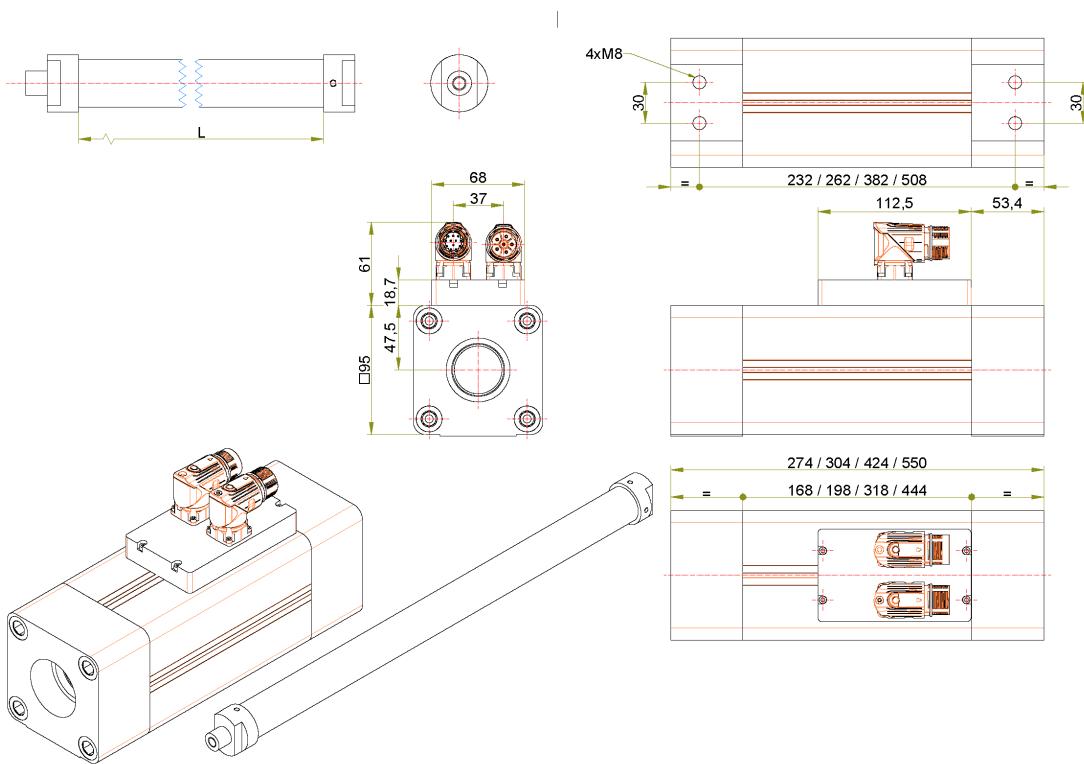
**ETT050**

Part Number Codification	Rod "F"		Rod "N"		Rod "M"		Rod "G"		Stroke		
	Length [mm]	Weight [kg]	S1 [mm]	S2 [mm]	S3 [mm]						
0254	254	0.759	274	0.758	259	0.758	264	0.76	30		
0284	284	0.866	304	0.865	289	0.865	294	0.867	60	30	
0314	314	0.973	334	0.972	319	0.972	324	0.974	90	60	
0344	344	1.08	364	1.079	349	1.079	354	1.081	120	90	
0374	374	1.187	394	1.186	379	1.186	384	1.188	150	120	
0404	404	1.294	424	1.293	409	1.293	414	1.295	180	150	
0434	434	1.401	454	1.4	439	1.4	444	1.402	210	180	30
0464	464	1.508	484	1.507	469	1.507	474	1.509	240	210	60
0494	494	1.614	514	1.613	499	1.613	504	1.615	270	240	90
0524	524	1.721	544	1.72	529	1.72	534	1.722	300	270	120
0554	554	1.828	574	1.827	559	1.827	564	1.829	330	300	150
0584	584	1.935	604	1.934	589	1.934	594	1.936	360	330	180
0614	614	2.042	634	2.041	619	2.041	624	2.043	390	360	210
0644	644	2.149	664	2.148	649	2.148	654	2.15	420	390	240
0674	674	2.256	694	2.255	679	2.255	684	2.257	450	420	270
0704	704	2.363	724	2.362	709	2.362	714	2.364	480	450	300
0734	734	2.47	754	2.469	739	2.469	744	2.471	510	480	330
0764	764	2.576	784	2.575	769	2.575	774	2.577	540	510	360
0794	794	2.683	814	2.682	799	2.682	804	2.684	570	540	390
0824	824	2.79	844	2.789	829	2.789	834	2.791	600	570	420
0854	854	2.897	874	2.896	859	2.896	864	2.898	630	600	450
0884	884	3.004	904	3.003	889	3.003	894	3.005	660	630	480
0914	914	3.111	934	3.11	919	3.11	924	3.112	690	660	510
0944	944	3.218	964	3.217	949	3.217	954	3.219	720	690	540
Coil weight [kg]											1.54
											1.765
											3.005

Max rod length allowed 1500 mm.

## Dimensions

**ETT080**



## ETT - Length of Rod / Table of Stroke

**ETT080**

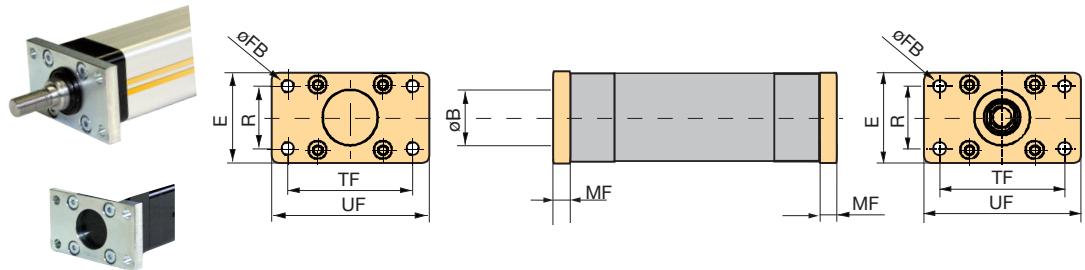
Part Number Codification	Rod "F"		Rod "N"		Rod "M"		Rod "G"		Stroke			
	Length [mm]	Weight [kg]	Length [mm]	Weight [kg]	Length [mm]	Weight [kg]	Length [mm]	Weight [kg]	S2 [mm]	S3 [mm]	S4 [mm]	S5 [mm]
0338	338	1.99	362	1.99	350	2.00	354	2.00	46			
0368	368	2.20	392	2.20	380	2.22	384	2.22	76	46		
0398	398	2.42	422	2.42	410	2.43	414	2.43	106	76		
0428	428	2.63	452	2.63	440	2.64	444	2.64	136	106		
0458	458	2.84	482	2.84	470	2.85	474	2.85	166	136		
0488	488	3.05	512	3.05	500	3.07	504	3.07	196	166	46	
0518	518	3.27	542	3.27	530	3.28	534	3.28	226	196	76	
0548	548	3.48	572	3.48	560	3.49	564	3.49	256	226	106	
0578	578	3.69	602	3.69	590	3.71	594	3.71	286	256	136	
0608	608	3.90	632	3.90	620	3.92	624	3.92	316	286	166	40
0638	638	4.12	662	4.12	650	4.13	654	4.13	346	316	196	70
0668	668	4.33	692	4.33	680	1.34	684	4.34	376	346	226	100
0698	698	4.54	722	4.54	710	4.56	714	4.56	406	376	256	130
0728	728	4.75	752	4.75	740	4.77	744	4.77	436	406	286	160
0758	758	4.97	782	4.97	770	4.98	774	4.98	466	436	316	190
0788	788	5.18	812	5.18	800	5.19	804	5.19	496	466	346	220
0818	818	5.39	842	5.39	830	5.41	834	5.41	526	496	376	250
0848	848	5.60	872	5.60	860	5.62	864	5.62	556	526	406	280
0878	878	5.82	902	5.82	890	5.83	894	5.83	586	556	436	310
0908	908	6.03	932	6.03	920	6.04	924	6.04	616	586	466	340
0938	938	6.24	962	6.24	950	6.26	954	6.26	646	616	496	370
0968	968	6.45	992	6.45	980	6.47	984	6.47	676	646	526	400
0998	998	6.67	1022	6.67	1010	6.68	1014	6.68	706	676	556	430
1028	1028	6.88	1052	6.88	1040	6.89	1044	6.89	736	706	586	460
								Coil weight [kg]	4.4	5	7	9.55

Max rod length allowed 1750 mm

## Accessories and Options

### Mounting Methods

#### Front and Rear Plate



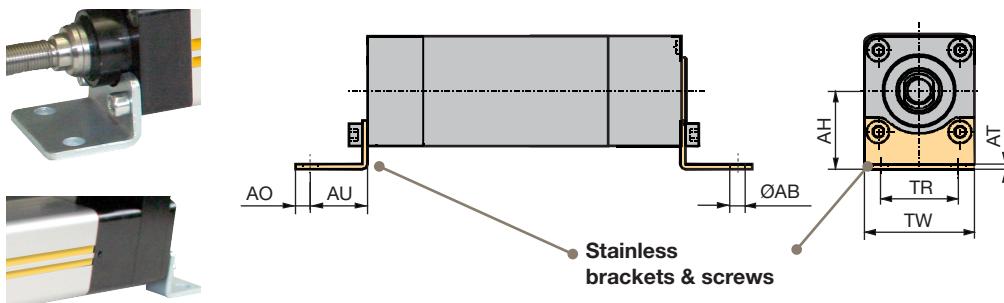
Front and rear plate dimensions

	Order no. (1 piece)	UF	E	TF	ØFB	R	MF	ØB
		[mm]						
<b>ETT032</b>	0112.918	80	48	64	7	32	10	30
<b>ETT050</b>	0122.918	110	65	90	9	45	12	40
<b>ETT080</b>	0132.918	150	95	126	12	63	16	60

Spare parts delivery includes screws for mounting.

Please note that front and rear plate as spare parts must be ordered separately.

#### Mounting Brackets

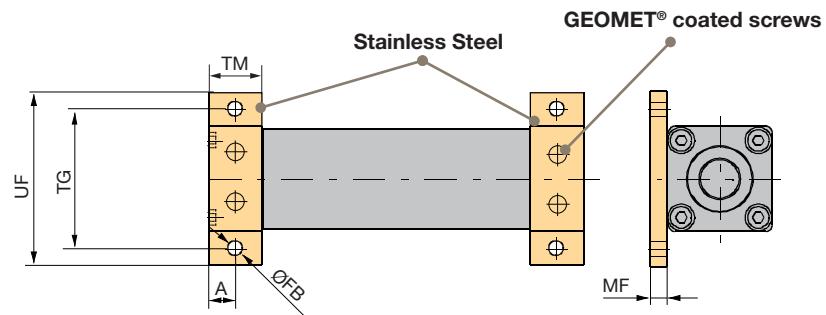
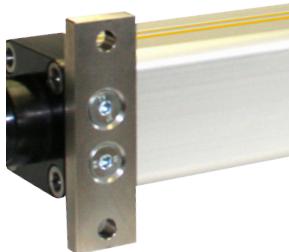


	Order no. Front & Terminal bracket	AH	AT	TR	ØAB (H14)	AO	AU	TW
		[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
<b>ETT032</b>	0112.916	32	4	32	7	8	24	46.5
<b>ETT050</b>	0122.916	44	4	45	9	12	32	63.5
<b>ETT080</b>	0132.916	47	6	72	13.5	15	41	95

Spare parts delivery includes screws for mounting.

\* For protection classes, we recommend GEOMET® coated screws (thin layer corrosion protection).

## Mounting Flanges



	Order no. (2 piece)	TG	UF	ØFB	TM	MF	A
		[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
<b>ETT032</b>	0112.917E	62	78	6.6	25	8	12.5
<b>ETT050</b>	0122.917E	84	104	9	30	10	15
<b>ETT080</b>	0132.917E	120	144	13.5	40	12	20

Spare parts delivery includes screws for mounting.

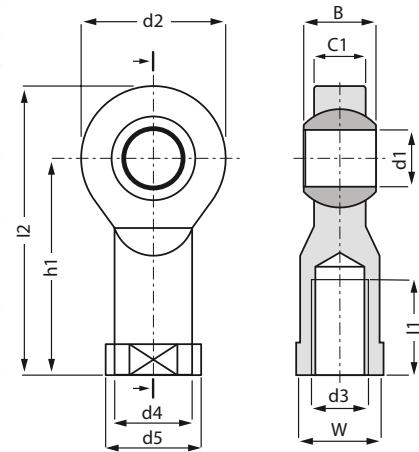
\* For protection classes, we recommend GEOMET® coated screws (thin layer corrosion protection).

## Cylinder Rod Version

### Plastic Swivel Rod Eye



KBRM	-05	-06	-08	-10
	ETT025	ETT032	ETT050	ETT080
<b>d1 E10</b>	5	6	8	10
<b>d2</b>	18	20	24	30
<b>d3</b>	M5	M6	M8	M10
<b>d4</b>	9.0	10.0	13.0	15
<b>d5</b>	12.0	13.0	16.0	19
<b>C1</b>	6.0	7.0	9.0	10.5
<b>B</b>	8	9	12	14
<b>h1</b>	27	30	36	43
<b>I1</b>	10	12	16	20
<b>I2</b>	36	40	48	58
<b>W</b>	SW09	SW11	SW14	SW17
<b>Pitch</b>	30°	29°	25°	25°



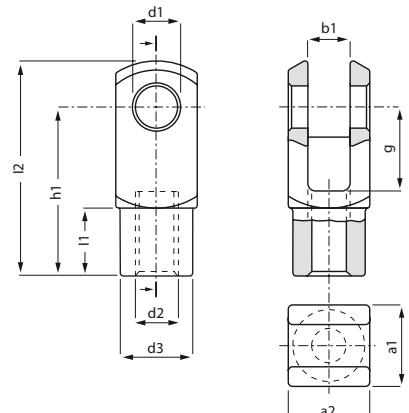
manufactured by igus®

### Plastic Rod Clevis



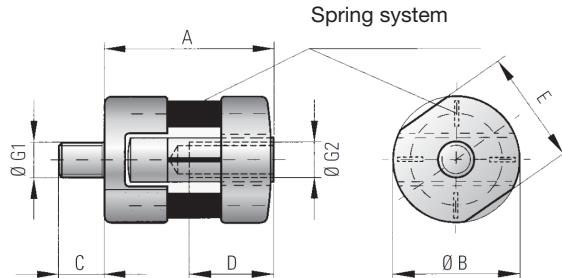
GERM	-05	-06	-08	-10
	ETT025	ETT032	ETT050	ETT080
<b>d1 H9</b>	5	6	8	10
<b>g h11</b>	12	12	16	20
<b>a1 +0.3 / -0.16</b>	12	12	16	20
<b>a2 +0.3 / -0.16</b>	12	12	16	20
<b>b1 B13</b>	6	6	8	10
<b>d2 6H *</b>	M5	M6	M8	M10
<b>d3 +0.3 / -0.3</b>	10.0	10.0	14.0	18.0
<b>I2 +0.5 / -0.5</b>	31.0	31.0	42.0	52.0
<b>h1 +0.3 / -0.3</b>	24.0	24.0	32.0	40.0
<b>I1 +0.2 / -0.2</b>	9.0	9.0	12.0	15.0

\* Thread tolerance



manufactured by igus®

## Alignment Coupler



manufactured by R+W®

LK	70	150	300	500
	ETT025	ETT032	ETT050	ETT080
<b>Pressure force [N]</b>	70	150	300	500
<b>A</b>	24	33	41.5	52
<b>B</b>	18	22	30	42
<b>G1/2</b>	M5	M6	M8	M10
<b>G1/2* [Nm]</b>	4	7	18	30
<b>C</b>	6.5	8	10	13
<b>D</b>	10	12	16	20
<b>E</b>	16	20	27	38
<b>Mass [g]</b>	11	23	57	135
<b>Lateral restoring force (max) (N)</b>	10	18	48	96
<b>Lateral mov. (max) [mm]</b>	0.5	0.5	0.5	0.7
<b>Angular mov. (max)</b>	1.5°	1.5°	1.5°	1.5°

\* Max. tightening torque thread

All alignment coupler sizes are sized on continuous force of ETT. For other force options, please contact Parker

## Sealing Rings

ETT motors can be equipped with sealing rings for protecting the coil from contaminants, spray water or excessive grease loss; thus increasing the motor service life.



Sealing rings of special design	
<b>Material</b>	Thermoplastic polyurethane elastomer
<b>Colour</b>	Green
<b>Temperature range</b>	From - 30 °C to + 100 °C
<b>Hardness</b>	47 ± Shore D
<b>Ageing resistance</b>	Light
	Very good
	Ozone
	Good
<b>Media resistance</b>	
Mineral oils, greases	Yes*
Highly blended/synthetic lubricants	No*
Aggressive	No*

Adding sealing rings will change some ETT requirements:

- rod must be lubricated with grease type RHEOSIL 500F
- speed is limited up to 3 m/s max
- temperature range changes to -30 °C... + 100 °C
- stroke of the rod decreases
- rotating movements are not allowed
- rod needs to be kept clean

\*Please contact your nearest sales office

## ETT with Slide Guide System

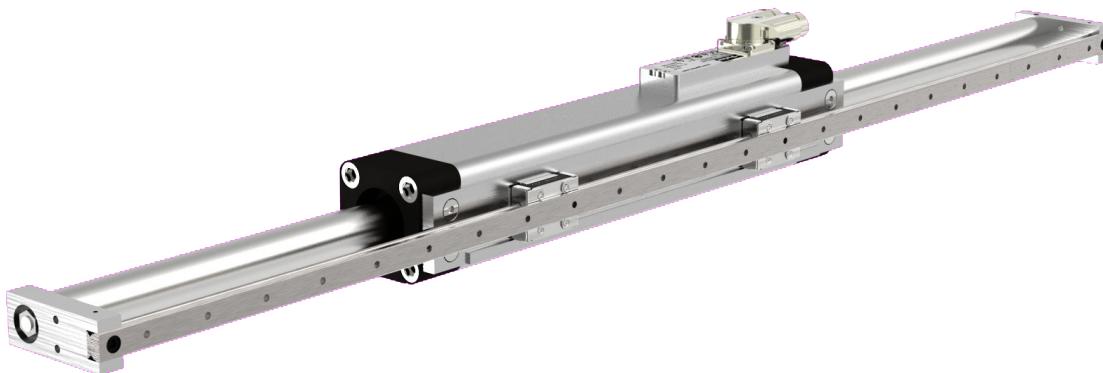
As the system is based on polymer plain bearings, the motor shaft can only sustain limited radial loads; the slide guide system of the ETT motor makes it the ideal solution for applications requiring an anti-rotational device and where lateral force occurs.

Two different configuration layouts are available:

### ETT with Slide Guide System

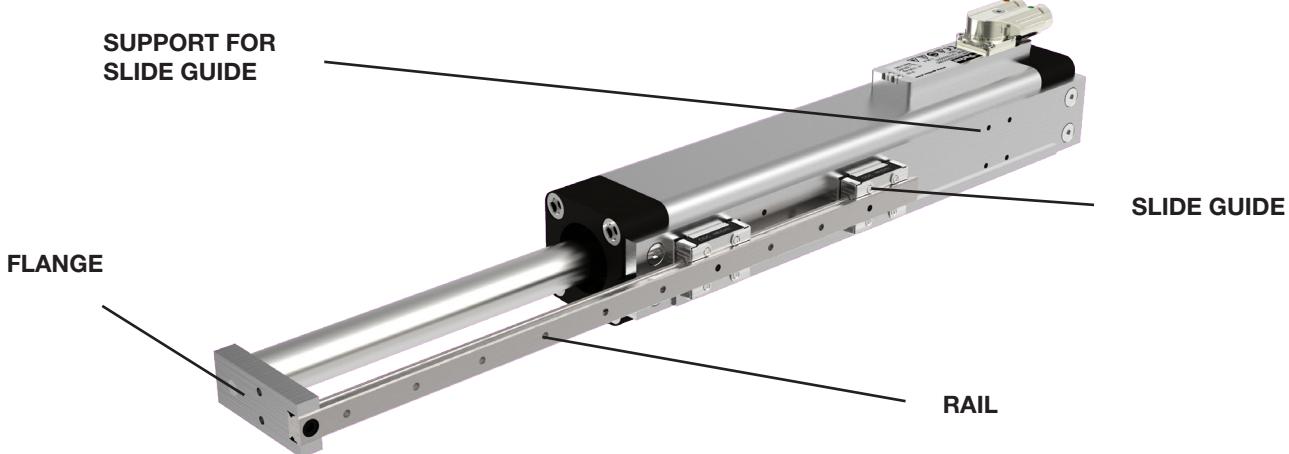


### Coil movement for long stroke and heavy load



Both solutions use an external system of block bearing, rail and rod-end designed for a specific application. An external linear feedback can be added on the mechanical system to improve the precision and repeatability of the system. With coil movement it's recommended to remove the bush bearing, it's mandatory for long strokes.

### Structure of the Slide Guide System



RAIL		SLIDE GUIDE	
Series	<b>ETT-LR</b>	Series	<b>ETT-LC</b>
Rail type	<b>1</b> Rail option	Rail type	Slide guide option
	<b>025</b> Type NB		<b>1</b> Type NB
	<b>032</b> n.a.		<b>025</b> n.a.
ETT motor size	<b>032</b> Designed for motor size 032 - 9 mm size	ETT motor size	<b>032</b> Designed for motor size 032 - 9 mm size
	<b>050</b> Designed for motor size 050 - 15 mm size		<b>050</b> Designed for motor size 050 - 15 mm size
	<b>080</b> Designed for motor size 080 - 20 mm size		<b>080</b> Designed for motor size 080 - 20 mm size
Length	<b>xxx</b> *See table of rod length		

FLANGE		SUPPORT FOR SLIDE GUIDE	
Series	<b>ETT-LF</b>	Series	<b>ETT-LA</b>
Side of flange	<b>F</b> Flange option	025	Metal support for slide guide option
	<b>R</b> Front flange	<b>025</b>	n.a.
	<b>R</b> Rear flange	<b>032</b>	Designed for motor size 032 - 9 mm size
	<b>025</b> n.a.	<b>050</b>	Designed for motor size 050 - 15 mm size
ETT motor size	<b>032</b> Designed for motor size 032 - 9 mm size	<b>080</b>	t.b.d.
	<b>050</b> Designed for motor size 050 - 15 mm size	<b>S1</b>	Winding: Serial, Stack Length 1 - not available for size 080
	<b>080</b> Designed for motor size 080 - 20 mm size	<b>S2</b>	Winding: Serial, Stack Length 2
		<b>S3</b>	Winding: Serial, Stack Length 3
		<b>S4</b>	Winding: Serial, Stack Length 4 - only size 080
		<b>S5</b>	Winding: Serial, Stack Length 5 - only size 080

The solution can be ordered as a complete system mounted and tested.

The slide guide system structure results in a reduction of ETT performance due to additional moving mass and friction. ETT with slide guide system is an ideal solution for easy integration into pick and place gantries and general purpose material handling machines.

## Feedback

### Internal position sensor-analogue sin/cos

The position sensor outputs analogue, differential sine and cosine signals for providing position feedback. Shown below in the follow table the main features of sin/cos feedback.

	ETT025	ETT032	ETT050	ETT080
Pole pitch [mm]	60	60	60	60
Output current [mA]	50	50	50	50
Supply voltage [VDC]		5 ± 0.25		
Supply current [mA]		40 ± 10%		
Repeatability up to [µm]		± 50		

### Internal position sensor-incremental TTL

The incremental position sensor outputs have TTL line drives signals, A and B, /A and /B without track of zero. The resolution is programmable and the default value is 2048 increments.

	ETT025	ETT032	ETT050	ETT080
Pole pitch [mm]	60	60	60	60
Output signals		A, B, /A, /B		
Supply voltage [VDC]		5 ± 0.25		
Supply current [mA]		100 ± 10%		
Repeatability up to [µm]		± 50		
Resolution with 2048 increments [µm]		29.3		
System accuracy [mm]		± 0.5		
Error of linearity		< 1%		
Max resolution		24 bit		

### Internal position sensor-BIIS-C

The internal feedback allows to have a BISS-C interface option. The electronic board contains an integrated sensor, interpolation electronics and motor parameters as electronic data sheet (EDS).

	ETT025	ETT032	ETT050	ETT080
Pole pitch [mm]	60	60	60	60
Output signals		BISS-C RS485 serial		
Supply voltage [VDC]		5 ± 0.25		
Supply current [mA]		100 ± 10%		
Repeatability up to [µm]		± 50		
Resolution with 2048 increments [µm]		29.3		
System accuracy [mm]		± 0.5		
Error of linearity		< 1%		
Max resolution		8192 increments		

## External Linear Encoders

To achieve highest accuracy, the most popular feedback device for linear motor positioning systems is the linear encoder. There are two variants of linear encoders available; magnetic and optical.

<b>MSK500010KE1</b>	Incremental, digital interface, resolution 1 µm <ul style="list-style-type: none"><li>• Magnetic encoder</li><li>• Max. resolution up to 1 µm</li><li>• Repeat accuracy ±0.01 mm</li><li>• Status LED display</li><li>• Works with magnetic band MB500</li><li>• Reading distance up to 2 m</li></ul>
<b>LIC 2117</b>	Absolute, EnDat interface, resolution 0.1 µm <ul style="list-style-type: none"><li>• Optical encoder</li><li>• Max. resolution up to 0.1 µm</li><li>• Repeat accuracy ±15 µm</li><li>• EnDat2.2</li><li>• Reading distance up to 3 m</li></ul>

## Cables and connectors

All cable kits are optimally configured for our servo products line. The characteristics of the cables include: low adhesion, halogen free and flame-retardant according to the requirements DIN VDE 0472. Resistant to oil, grease, coolant and lubricants.

### Motor connection power cable

Type	ETT-CAP
<b>Cable design</b>	
Conductor material	Stranded copper
Core structure	(3 + T) x 1.5 mm <sup>2</sup>
Core insulation	TEO-Flexene®
Outer sheath	Polyurethane
Colour sheath	Orange RAL2003
<b>Technical data</b>	
Rated voltage	Power: 600/1000 V
Dielectric strength	Power: 4000 V
Insulation resistance	Power: > 2500 MOhm x km
Minimum bending radius	7.5 x diam. unsupported chain 10 x diam. long travel
Max. speed	240 m/min.
Max. acceleration	20 m/sec <sup>2</sup>
Cycles	10000000
Operating temperature	-30 + 80 °C
Outer diameter	8.5 mm

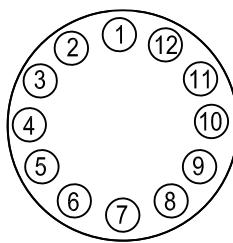
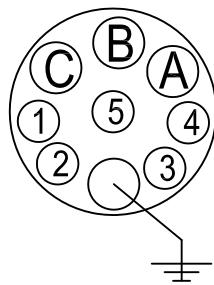


### Motor connection signal cable

Type	ETT-CAS
<b>Cable design</b>	
Conductor material	Stranded copper
Core structure	[3x(2x0.14 SK)+2x(0.50 SK)] SK
Core insulation	TPE-E
Outer sheath	Polyurethane
Colour sheath	Green RAL6018
<b>Technical data</b>	
Rated voltage	30 V
Dielectric strength	1500 V
Insulation resistance	> 10 MOhm x km
Minimum bending radius	90 mm
Max. speed	240 m/min.
Max. acceleration	20 m/sec <sup>2</sup>
Cycles	≥ 5000000
Operating temperature	-30 + 80 °C
Outer diameter	8.4 mm



## Layout and Connectors ETT025 - ETT050



**Power connector**

Pin	Description
A	U
B	W
C	V
PE	PE
1	n.c.
2	n.c.
3	n.c.
4	n.c.
5	n.c.

Type
CONMOTYF Female connector

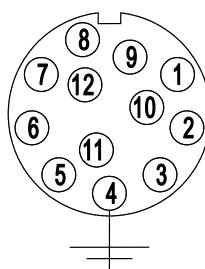
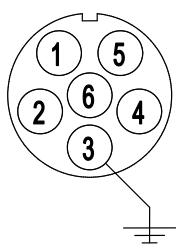
**Feedback connector**

Pin	Description
1	COS -
2	COS +
3	n.c.
4	KTY84 -
5	KTY84 +
6	n.c.
7	SIN -
8	SIN +
9	n.c.
10	+5 V
11	n.c.
12	GND - shield

Type
CONRESYF Female connector

## Layout and Connectors ETT080



**Power connector**

Pin	Description
1	U
2	V
3	GND - shield
4	n.c.
5	n.c.
6	W

Type
CONMOT82F Female connector

**Feedback connector**

Pin	Description
1	SIN -
2	SIN +
3	n.c.
4	GND - shield
5	n.c.
6	n.c.
7	EXCT -
8	KTY -
9	KTY +
10	EXCT +
11	COS +
12	COS -

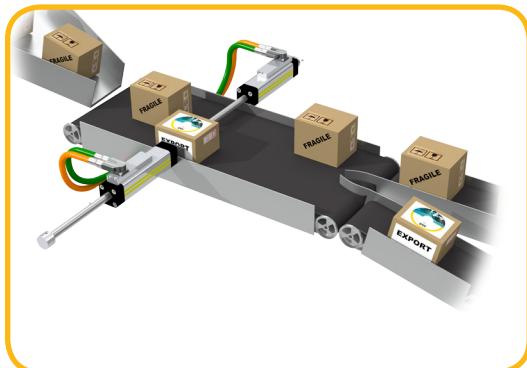
Type
CONRES82F Female connector

## Application Examples



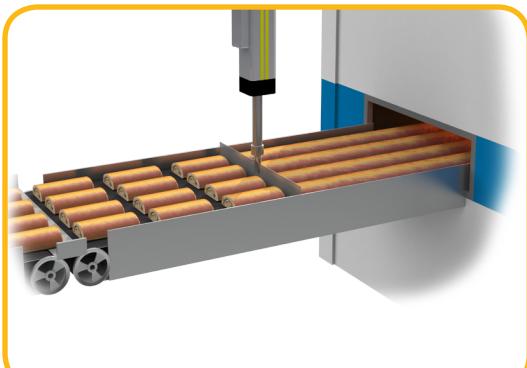
### Stacking

The ETT manages the stacking of CD's after the printing section. Thanks to the complete and ready to use direct drive solution, no more time is spent in assembling and aligning different elements (gearbox, belts and pulley, motor,etc).



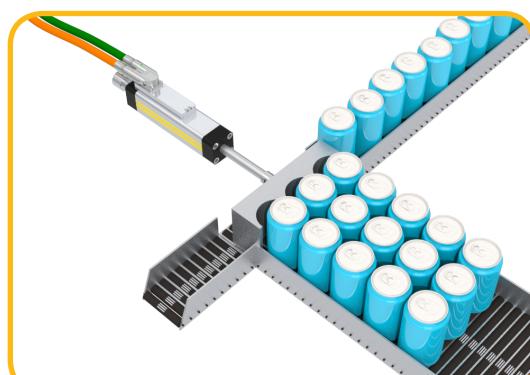
### Sorting

A supervision system manages the boxes and moves them onto different conveyors following their layout. Both ETT tubular motors are synchronised and can quickly adapt to the box's dimensions. The quick positioning is the main advantage for system performance.



### Cutting

Here the ETT function is to cut the material all to the same length. The ETT high force level and synchronization with the conveyor are key benefits in this application. The level of control offered by the ETT means that it is easy to change the format of the material.



### Re-positioning

ETT is used to accurately reposition products on conveyors. The flexible dynamic positioning offered by the electric tubular motor guarantees the perfect alignment for different product formats whilst fewer components improves energy efficiency.

## Step by Step Selection Process

The following sizing steps help to choose the most suitable electric tubular motor.

1. Select an ETT using estimated application data.
2. Calculate the actually required application data following the dimensioning steps described below.
3. If your application's requirements exceed a maximum value, please choose a larger electro cylinder and recheck the maximum values. Perhaps, a smaller tubular motor can also meet the requirements.

Step	Application data	Selection
1	Accuracy, ambient conditions	Check the basic conditions for the use of the ETT in your application.
2	Required space	Check the space available in your application and choose the motor mounting option: rod movement or coil movement
3	Select stroke	Selection of the desired stroke: Determine required stroke from usable stroke and safety travels select the desired stroke from the list of standard strokes or, if the desired stroke is not listed: Define the length of the usable stroke in steps of one mm. Caution! Please respect the minimum and the maximum possible stroke
4	Maximum force required	Determination of the maximum required axial force (traction and thrust force). With evaluation of duty cycle
5	Select position mounting	Check if the ETT orientation is vertical or horizontal
6	Maximum speed	Selection of the maximum speed required for the application
7	Application cycle	Please check the application cycle
8	Permissible thrust force taking the buckling risk into consideration	Check the maximum thrust force depending on the stroke and the mounting variant. Maybe your application can also be realized with a different mounting variant allowing to attain the maximum thrust force
10	Permissible side load	Determine the lateral forces of your application and compare them to the permissible lateral forces (depending on the stroke)
11	Mounting type	Selection of ETT mounting accessories
12	Rod connection	Selection of the rod mounting type

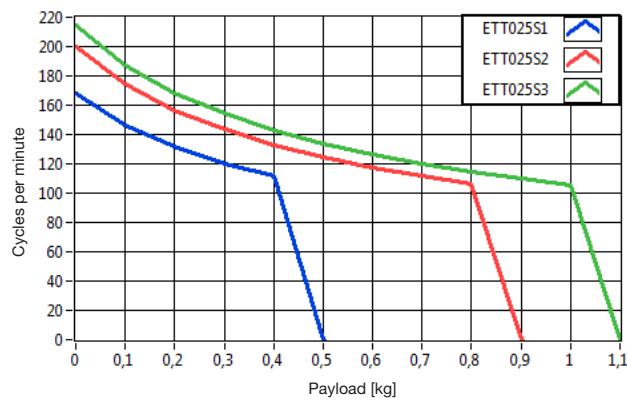
Automated sizing can be done with the help of "ETTsizing" software tool to simplify the process:  
[www.ettsizing.eu](http://www.ettsizing.eu)

## ETT Range Sizing

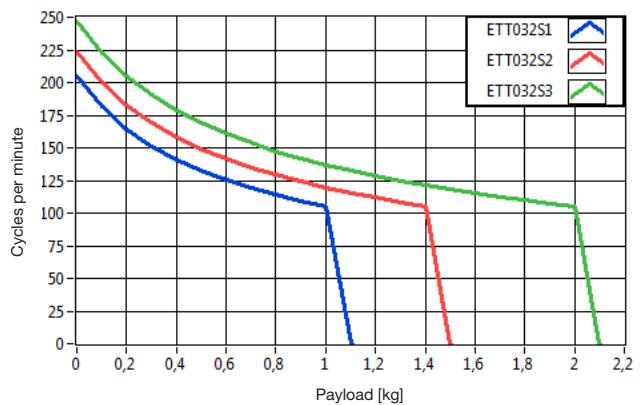
In order to simplify the representation, we assumed boundary conditions which must be adhered to without exception in your application, otherwise the product combinations suggested here might not work. In this case, the application must be dimensioned conventionally.

The following graphs show the combination of the maximum cycles per minute and maximum payload for each size of motor with the assumption of: Stroke 90 mm, Triangular profile, Cycle S3 – 5%, Without thrust force.

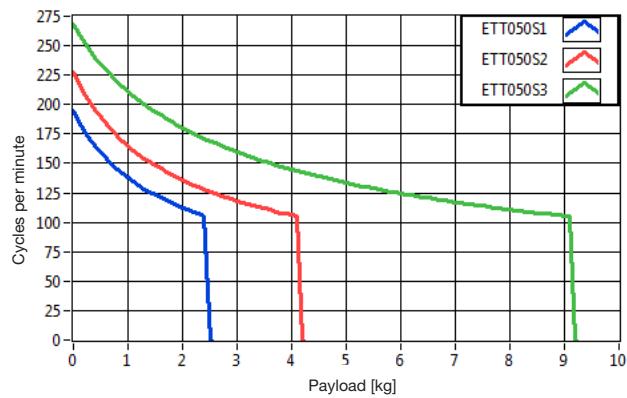
ETT025



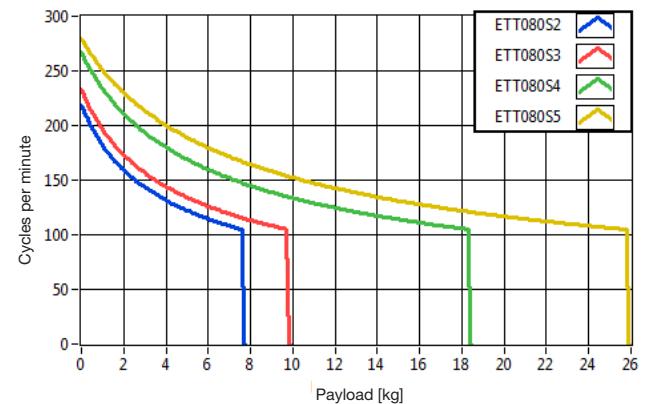
ETT032



ETT050



ETT080

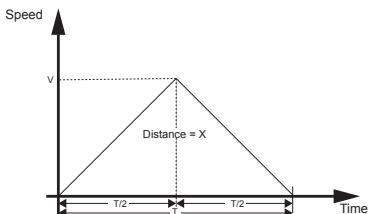


## Common Motion Profile Formulas

### Triangular Profile 1/2, 1/2

Accelerate to speed and decelerate back to original speed or zero, rest and repeat the process as needed.

This is very simple and is common in applications such as Pick & Place.

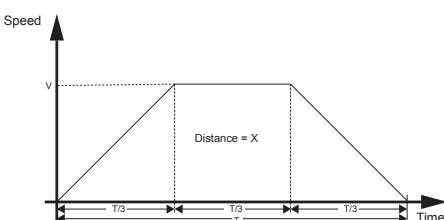


### Trapezoidal Profile

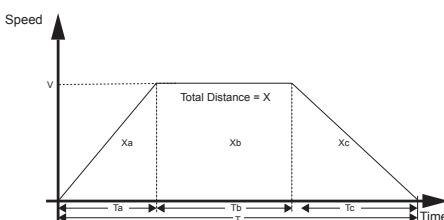
Accelerate to constant speed, travel at a constant speed and then decelerate back to original speed or zero. This is common in applications such as scanning inspection. There are two types, the 1/3 Trapezoidal Profile and the Variable Trapezoidal Profile.

Item	Symbol	Unit
Stroke	X	mm
Velocity	V	m/s
Acceleration time	T <sub>a</sub>	s
Continuous time	T <sub>b</sub>	s
Deceleration time	T <sub>c</sub>	s
Settling time	T <sub>s</sub>	s
Waiting time	T <sub>w</sub>	s

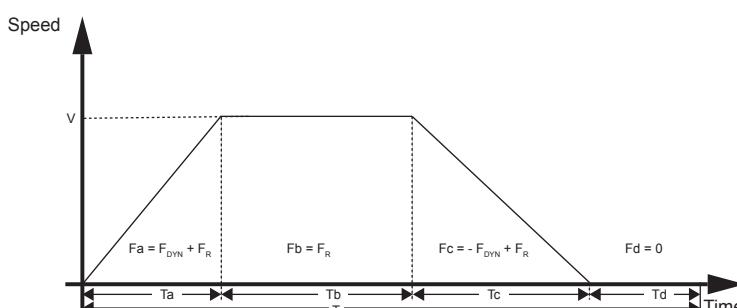
Solve for	Have	X (m) T (sec)	V (m/sec) T (sec)	A (m/sec <sup>2</sup> ) T (sec)	A (m/sec <sup>2</sup> ) V (m/sec)
Distance X(m)			X = (1/2) * V * T	X = (1/4) * A * T <sup>2</sup>	X = (V <sup>2</sup> /A)
Velocity V (m/sec)	V = 2 <sup>*</sup> (X/T)			V = (A*T)/2	V = √(A*X)
Acceleration A (m/sec <sup>2</sup> )	A = 4 <sup>*</sup> (X/T <sup>2</sup> )	A = 2 * (V/T)			A = V <sup>2</sup> /X



Solve for	Have	X (m) T (sec)	V (m/sec) T (sec)	A (m/sec <sup>2</sup> ) T (sec)	A (m/sec <sup>2</sup> ) V (m/sec)
Distance X(m)			X = (2/3) * V * T	X = (1/4.5)*A*T <sup>2</sup>	X = 2 * (V <sup>2</sup> /A)
Velocity V (m/sec)	V = 1.5 * (X/T)			V = (A*T)/3	V = √(A*X)/2
Acceleration A (m/sec <sup>2</sup> )	A = 4.5 * (X/T <sup>2</sup> )	A = 3 * (V/T)			A = 2 * (V <sup>2</sup> /X)



Solve for	Have	X (m) T (sec)	V (m/sec) T (sec)	A (m/sec <sup>2</sup> ) T (sec)	A (m/sec <sup>2</sup> ) V (m/sec)
Distance X(m)			X = V * T/2	X = (A*T <sup>2</sup> )/2	X = V <sup>2</sup> /(2 * A)
Velocity V (m/sec)	V = (2 * X)/T			V = A * T	V = √(2 * A)/X
Acceleration A (m/sec <sup>2</sup> )	A = (2 * X)/T <sup>2</sup>	A = V/T			A = V <sup>2</sup> /(2 * X)



$$\text{Peak force } F_{\text{peak}} = \max (F_a, F_b, F_c, F_d)$$

$$\text{RMS Force } F_{\text{RMS}} = \sqrt{\frac{F_a^2 * T_a + F_b^2 * T_b + F_c^2 * T_c + F_d^2 * T_d}{T_a + T_b + T_c + T_d}}$$

### Force Formula

Dynamic force	F <sub>DYN</sub> = m * a
Friction force	F <sub>r</sub> = μ * F <sub>N</sub>
Normal force	F <sub>N</sub> = cos α * F <sub>G</sub>
Gravity force	F <sub>G</sub> = m * g

Item	Symbol	Unit
Gravity	g	9.81 m/s <sup>2</sup>
Friction coefficient	μ	
Moving mass	m	kg
Angle of the inclined surface	α	°
Acceleration time	T <sub>a</sub>	s
Constant speed time	T <sub>b</sub>	s
Deceleration time	T <sub>c</sub>	s
Waiting time	T <sub>d</sub>	s

## Servo Drives Products



### Compact Servo Drive SLVD-N

SLVD-N is the family of compact digital servo drives for brushless motors. In addition to positioning applications with trapezoidal profile, electrical shaft, electronic cam, spindle orientation, simulator of stepper motor and torque control, it holds a PLC inside able to talk to the most common industrial programming systems, giving a great freedom of use of the inputs and outputs. It also allows the development of additional configurations to the basis features of the drive, such as gains adjustment of the loop in relation to speed or space, torque monitoring used for tools etc.

Model	Continuous current [A]	Peak current [A]	Size
<b>SLVD1N</b>	1.25	2.5	1
<b>SLVD2N</b>	2.5	5	
<b>SLVD5N</b>	5	10	
<b>SLVD7N</b>	7	14	
<b>SLVD10N</b>	10	20	2

### Intelligent Servo Drive Compax 3

Compax3 is Parker Hannifin's global servo drive. The drive series includes single and multi axis drives as well as hydraulic controllers. It features a power range from 1 to 109 kVA.

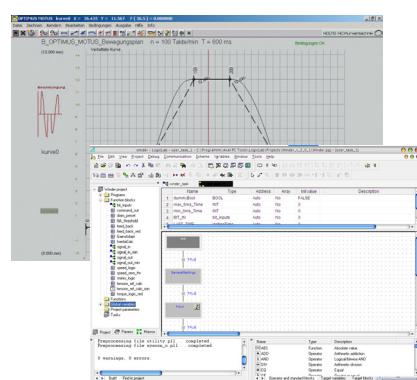
The servo drives are developed and manufactured in Germany. As a global servo drive controller, Compax3 is available all over the world. Service and support sites are located in the vicinity of all major industry locations - worldwide. The "Parker Authorized Distribution Partners" play an important role in this context - well-trained and experienced application and support specialists will provide professional support in any situation.

Device	Current [A]		Supply Voltage	Power [kVA]
Compax3	I <sub>cont.</sub>	I <sub>peak (&lt;5 s)</sub>		
S025V2	2.5	5.5	1 * 230/240 VAC	1,0
S063V2	6.3	12.6		2,5
S100V2	10	20	3 * 230/240 VAC	4,0
S150V2	15	30		6,0
S015V4	1.5	4.5		1.25
S038V4	3.8	9.0	3 * 400/480 VAC	3.1
S075V4	7.5	15		6.2



### Software and Tools

MotionWiz and C3 Servo Manager configuration software are available to configure the SLVD-N and Compax3 system with just a few clicks. The software features an easy and "friendly" interface to speed up installation, optimisation and diagnostics procedures. To simplify configuration, the software shows a typical Windows® environment on the monitor with dialogue windows and toolbars.



## Order Code

### ETT Electric Tubular Motor (Complete Unit)

Order example	1	2	3	4	5	6	7	8	9
	ETT	032	S1	CS	M	N	....	C	

#### 1 Type

**ETT** Electric Tubular Motor

#### 2 Size

- 025** ISO 6432 - Bore 25 mm
- 032** ISO 6432 - Bore 32 mm
- 050** ISO 6432 - Bore 50 mm
- 080** ISO 6432 - Bore 80 mm

#### 3 Winding

- S1** Serial, Stack Length 1
- S2** Serial, Stack Length 2
- S3** Serial, Stack Length 3
- S4** Serial, Stack Length 4
- S5** Serial, Stack Length 5

#### 4 Connection and Feedback Type

- CS** Intercontec Connector  
(Springtec EEDA101NN0000000200) - Feedback  
Analogue SinCos 1 Vpp -
- CI** Intercontec Connector  
(Springtec EEDA101NN0000000200) - Feedback  
Incremental TTL
- CB** Intercontec Connector  
(Springtec EEDA101NN0000000200) - Feedback  
BISS-C
- 1S** Flying leads, Length 1 m, rear output -  
Feedback Analogue SinCos 1 Vpp - Only ETT025
- 2S** Flying leads, Length 2.5 m, rear output -  
Feedback Analogue SinCos 1 Vpp - Only ETT025
- 5S** Flying leads, Length 5 m, rear output -  
Feedback Analogue SinCos 1 Vpp - Only ETT025

#### 5 Rod End Mounting - Front / Rear

- M** Male Thread / Cap End  
(M5 ETT025, M6 ETT032, M8 ETT050, M10 ETT080)
- F** Female Thread / Cap End  
(M5 ETT025, M6 ETT032, M8 ETT050, M10 ETT080)
- N** Male Thread / Male Thread  
(M5 ETT025, M6 ETT032, M8 ETT050, M10 ETT080)
- G** Female Thread / Female Thread  
(M5 ETT025, M6 ETT032, M8 ETT050, M10 ETT080)
- X** Special  
(Customized version - Please contact Parker)

#### 6 Fixed Field

- N** Fixed field

#### 7 Stroke

- ..... Stroke length is in mm, four digits.
- ..... Example 30cm=0300. See table pages
- ..... 12,13,14,15 - column "Stroke".

#### 8 Protection Class

- C** IP67

#### 9 Customized Options

Blank for standard motors

## ETT Electric Tubular Motor (Rod only)

	1	2	3	4	5
Order example	ETT-R	032	M	....	

### 1 Type

**ETT-R** Electric Tubular Motor - Rod only

### 2 Size

**025** ISO 6432 - size 25

**032** ISO 6432 - size 32

**050** ISO 6432 - size 50

**080** ISO 6432 - size 80

### 3 Rod End Mounting - Front / Rear

**M** Male Thread / Cap End  
(M5 ETT025, M6 ETT032, M8 ETT050, M10 ETT080)

**F** Female Thread / Cap End  
(M5 ETT025, M6 ETT032, M8 ETT050, M10 ETT080)

**N** Male Thread / Male Thread  
(M5 ETT025, M6 ETT032, M8 ETT050, M10 ETT080)

**G** Female Thread / Female Thread  
(M5 ETT025, M6 ETT032, M8 ETT050, M10 ETT080)

**X** Special  
(Customized version - Please contact Parker)

### 4 Length

- ..... Rod length is in mm, four digits.
- ..... See tables pages 12,13,14,15 - column "Part Number Codification"

### 5 Customized Options

Blank for standard motors

## Order Code

### ETT Electric Tubular Motor (Coil only)

	1	2	3	4	5	6	7
Order example	ETT-C	032	S1	CS	N	C	

#### 1 Type

**ETT-C** Electric Tubular Motor - Coil only

#### 2 Size

- 025** ISO 6432 - Bore 25 mm
- 032** ISO 6432 - Bore 32 mm
- 050** ISO 6432 - Bore 50 mm
- 080** ISO 6432 - Bore 80mm

#### 3 Winding

- S1** Serial, Stack Length 1
- S2** Serial, Stack Length 2
- S3** Serial, Stack Length 3
- S4** Serial, Stack Length 4
- S5** Serial, Stack Length 5

#### 4 Connection and Feedback Type

- CS** Intercontec Connector  
(Springtec EEDA101NN000000002000) -  
Feedback Analogue SinCos 1 Vpp -
- CI** Intercontec Connector  
(Springtec EEDA101NN000000002000) -  
Feedback Incremental TTL
- CB** Intercontec Connector  
(Springtec EEDA101NN000000002000) -  
Feedback BISS-C
- 1S** Flying leads, Length 1 m, rear output -  
Feedback Analogue SinCos 1 Vpp - Only ETT025
- 2S** Flying leads, Length 2.5 m, rear output -  
Feedback Analogue SinCos 1 Vpp - Only ETT025
- 5S** Flying leads, Length 5 m, rear output -  
Feedback Analogue SinCos 1 Vpp - Only ETT025

#### 5 Fixed Field

- N** Fixed Field

#### 6 Protection Class

- C** IP67

#### 7 Customized Options

Blank for standard motors

## ETT Motor and Signal Cable

	1	2	3	4	5	6	7		
Order example	ETT-CAP	X	003	PM	-	Y1	SL	-	00

### 1 Cable Type

**ETT-CAP** Power cable for ETT

**ETT-CAS** Signal cable for ETT

### 2 Fixed Field

**X** Fixed field

### 3 Cable Length

**001** 1 m

**003** 3 m

**005** 5 m

**007** 7 m

**010** 10 m

**015** 15 m

**020** 20 m

### 4 Application Type

**PM** High flex cable

### 5 Connector

**Y1** Intercontec Y-TECH Connector

**I1** Intercontec M23 Connector

**X** Special Execution

### 6 Drive Type

**SL** SLVD-N Drive

**C3** Compax3

**63** 638 Drive

**IP** IPA Drive

### 7 Option

**00** No special option

Special customer drawing





# Parker's Motion & Control Technologies

At Parker, we're guided by a relentless drive to help our customers become more productive and achieve higher levels of profitability by engineering the best systems for their requirements. It means looking at customer applications from many angles to find new ways to create value. Whatever the motion and control technology need, Parker has the experience, breadth of product and global reach to consistently deliver. No company knows more about motion and control technology than Parker. For further info call 00800 27 27 5374



## Aerospace

### Key Markets

- Aftermarket services
- Commercial transports
- Engines
- General & business aviation
- Helicopters
- Launch vehicles
- Military aircraft
- Missiles
- Power generation
- Regional transports
- Unmanned aerial vehicles

### Key Products

- Control systems & actuation products
- Engine systems & components
- Fluid conveyance systems & components
- Fluid metering, delivery & atomization devices
- Fuel systems & components
- Fuel tank inerting systems
- Hydraulic systems & components
- Thermal management
- Wheels & brakes



## Climate Control

### Key Markets

- Agriculture
- Air conditioning
- Construction Machinery
- Food & beverage
- Industrial machinery
- Life sciences
- Oil & gas
- Precision cooling
- Process
- Refrigeration
- Transportation

### Key Products

- Accumulators
- Advanced actuators
- CO<sub>2</sub> controls
- Electronic controllers
- Filter driers
- Hand shut-off valves
- Heat exchangers
- Hose & fittings
- Pressure regulating valves
- Refrigerant distributors
- Safety relief valves
- Smart pumps
- Solenoid valves
- Thermostatic expansion valves



## Electromechanical

### Key Markets

- Aerospace
- Factory automation
- Life science & medical
- Machine tools
- Packaging machinery
- Paper machinery
- Plastics machinery & converting
- Primary metals
- Semiconductor & electronics
- Textile
- Wire & cable

### Key Products

- AC/DC drives & systems
- Electric actuators, gantry robots & slides
- Electrohydrostatic actuation systems
- Electromechanical actuation systems
- Human machine interface
- Linear motors
- Stepper motors, servo motors, drives & controls
- Structural extrusions



## Filtration

### Key Markets

- Aerospace
- Food & beverage
- Industrial plant & equipment
- Life sciences
- Marine
- Mobile equipment
- Oil & gas
- Power generation & renewable energy
- Process
- Transportation
- Water Purification

### Key Products

- Analytical gas generators
- Compressed air filters & dryers
- Engine air, coolant, fuel & oil filtration systems
- Fluid condition monitoring systems
- Hydraulic & lubrication filters
- Hydrogen, nitrogen & zero air generators
- Instrumentation filters
- Membrane & fiber filters
- Microfiltration
- Sterile air filtration
- Water desalination & purification filters & systems



## Fluid & Gas Handling

### Key Markets

- Aerial lift
- Agriculture
- Bulk chemical handling
- Construction machinery
- Food & beverage
- Fuel & gas delivery
- Industrial machinery
- Life sciences
- Marine
- Mining
- Mobile
- Oil & gas
- Renewable energy
- Transportation

### Key Products

- Check valves
- Connectors for low pressure fluid conveyance
- Deep sea umbilicals
- Diagnostic equipment
- Hose couplings
- Industrial hose
- Mooring systems & power cables
- PTFE hose & tubing
- Quick couplings
- Rubber & thermoplastic hose
- Tube fittings & adapters
- Tubing & plastic fittings

## Hydraulics

### Key Markets

- Aerial lift
- Agriculture
- Alternative energy
- Construction machinery
- Forestry
- Industrial machinery
- Machine tools
- Marine
- Material handling
- Mining
- Oil & gas
- Power generation
- Refuse vehicles
- Renewable energy
- Truck hydraulics
- Turf equipment

### Key Products

- Accumulators
- Cartridge valves
- Electrohydraulic actuators
- Human machine interfaces
- Hybrid drives
- Hydraulic cylinders
- Hydraulic motors & pumps
- Hydraulic systems
- Hydraulic valves & controls
- Hydrostatic steering
- Integrated hydraulic circuits
- Power take-offs
- Power units
- Rotary actuators
- Sensors

## Pneumatics

### Key Markets

- Aerospace
- Conveyor & material handling
- Factory automation
- Life science & medical
- Machine tools
- Packaging machinery
- Transportation & automotive

### Key Products

- Air preparation
- Brass fittings & valves
- Manifolds
- Pneumatic accessories
- Pneumatic actuators & grippers
- Pneumatic valves & controls
- Quick disconnects
- Rotary actuators
- Rubber & thermoplastic hose & couplings
- Structural extrusions
- Thermoplastic tubing & fittings
- Vacuum generators, cups & sensors

## Process Control

### Key Markets

- Alternative fuels
- Biopharmaceuticals
- Chemical & refining
- Food & beverage
- Marine & shipbuilding
- Medical & dental
- Microelectronics
- Nuclear Power
- Offshore oil exploration
- Oil & gas
- Pharmaceuticals
- Power generation
- Pulp & paper
- Steel
- Water/wastewater

### Key Products

- Analytical Instruments
- Analytical sample conditioning products & systems
- Chemical injection fittings & valves
- Fluoropolymer chemical delivery fittings, valves & pumps
- High purity gas delivery fittings, valves, regulators & digital flow controllers
- Industrial mass flow meters/controllers
- Permanent no-weld tube fittings
- Precision industrial regulators & flow controllers
- Process control double block & bleeds
- Process control fittings, valves, regulators & manifold valves

## Sealing & Shielding

### Key Markets

- Aerospace
- Chemical processing
- Consumer
- Fluid power
- General industrial
- Information technology
- Life sciences
- Microelectronics
- Military
- Oil & gas
- Power generation
- Renewable energy
- Telecommunications
- Transportation

### Key Products

- Dynamic seals
- Elastomeric o-rings
- Electro-medical instrument design & assembly
- EMI shielding
- Extruded & precision-cut, fabricated elastomeric seals
- High temperature metal seals
- Homogeneous & inserted elastomeric shapes
- Medical device fabrication & assembly
- Metal & plastic retained composite seals
- Shielded optical windows
- Silicone tubing & extrusions
- Thermal management
- Vibration damping

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#### Free phone: 00 800 27 27 5374

(from AT, BE, CH, CZ, DE, DK, EE, ES, FI, FR, IE, IL,  
IS, IT, LU, MT, NL, NO, PL, PT, RU, SE, SK, UK, ZA)

### US Product Information Centre

#### Toll-free number: 1-800-27 27 537

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